

# Machine Design-I

(Session-2018-19)

## Design Against Static Loading



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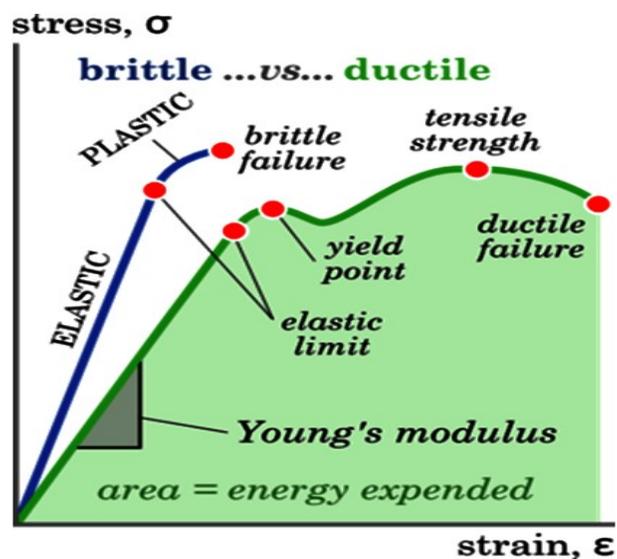
Design against static load

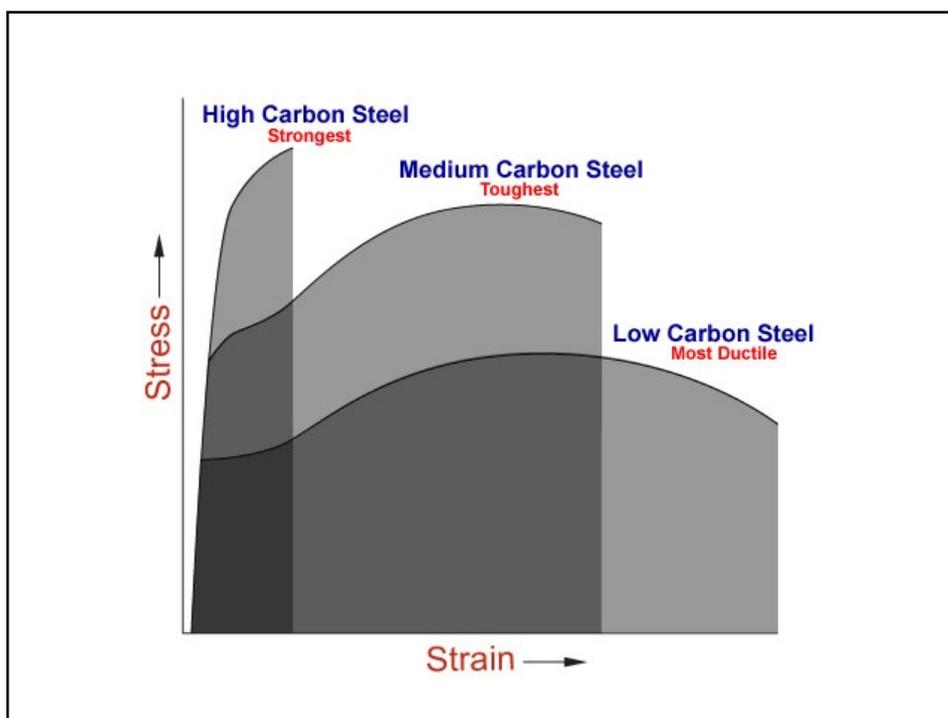
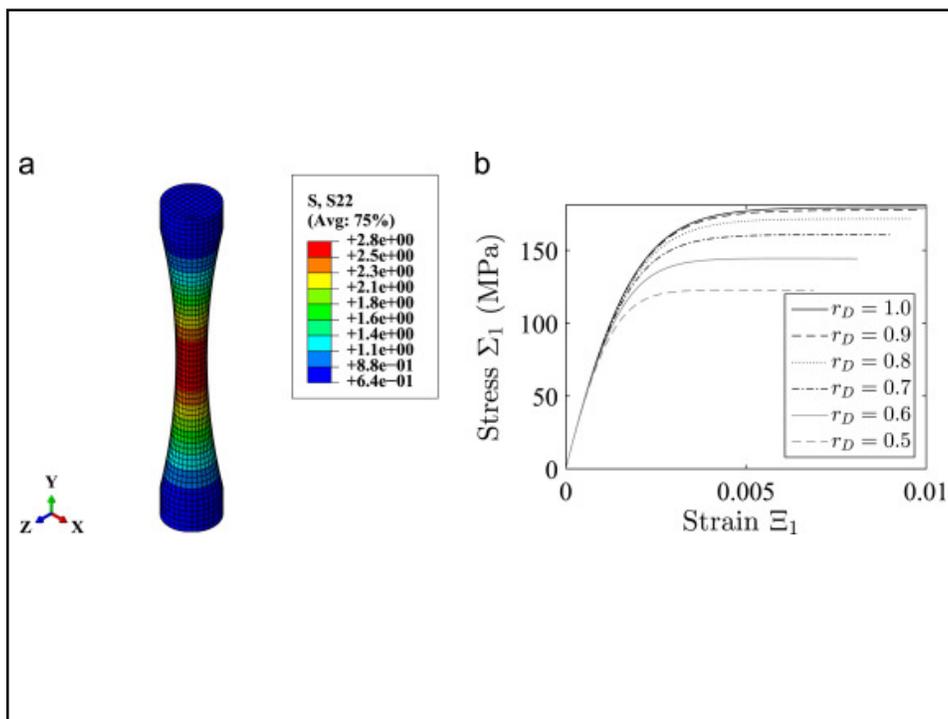
- A static load is defined as a force which is gradually applied to a mechanical component and which does not (or gradually) change its magnitude or direction with respect to time.
- Engineering Materials are classified in two groups –

Ductile and brittle

- Ductile has large tensile strain before fracture.  
6% more than brittle materials.

### Stress – strain curves for ductile and brittle materials





## Modes of failure

### **Failure by elastic deflection –**

- Ex. Transmission shafts for gears.
- Lateral or torsional rigidity is design criterion.
- Elastic deflection also results in buckling of columns or vibrations.
- Design should be based on permissible **lateral and torsional deflections.**

## Modes of failure (cont.....)

### **Failure by general yielding –**

- Ductile material loses its usefulness due to large amount of plastic deformation after yield point stress reached.
- Considerable portion is subjected to plastic deformation is general yielding.
- Design should be based on permissible **Yield Strength.**

## Modes of failure (cont.....)

### **Failure by fracture**

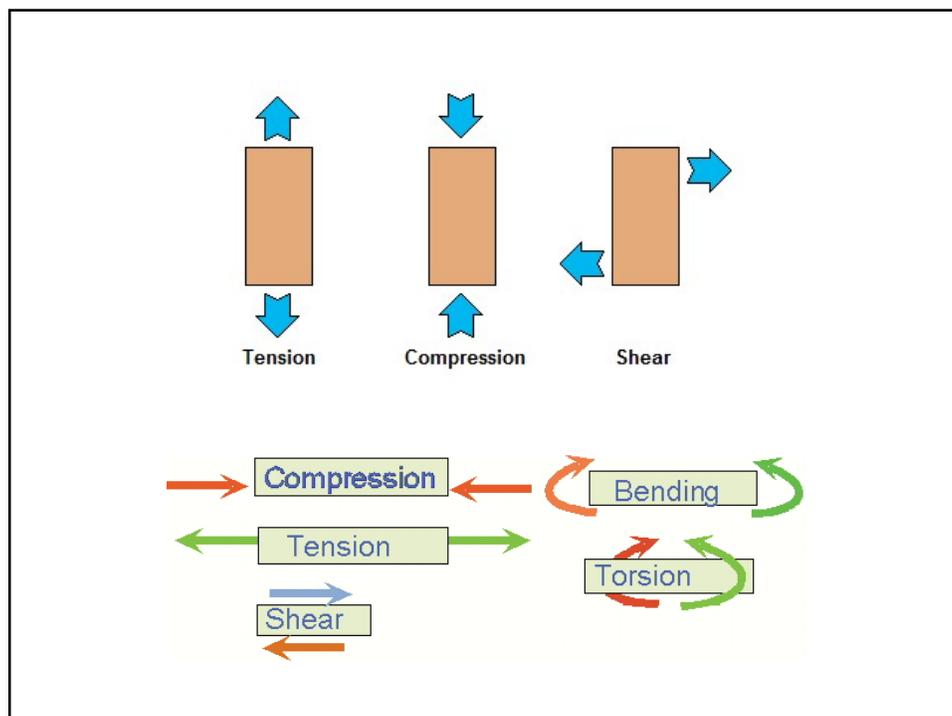
- Brittle materials fail because of the sudden fracture without any plastic deformation.
- The failure is sudden and total.
- Design should be based on permissible **Ultimate Strength**.

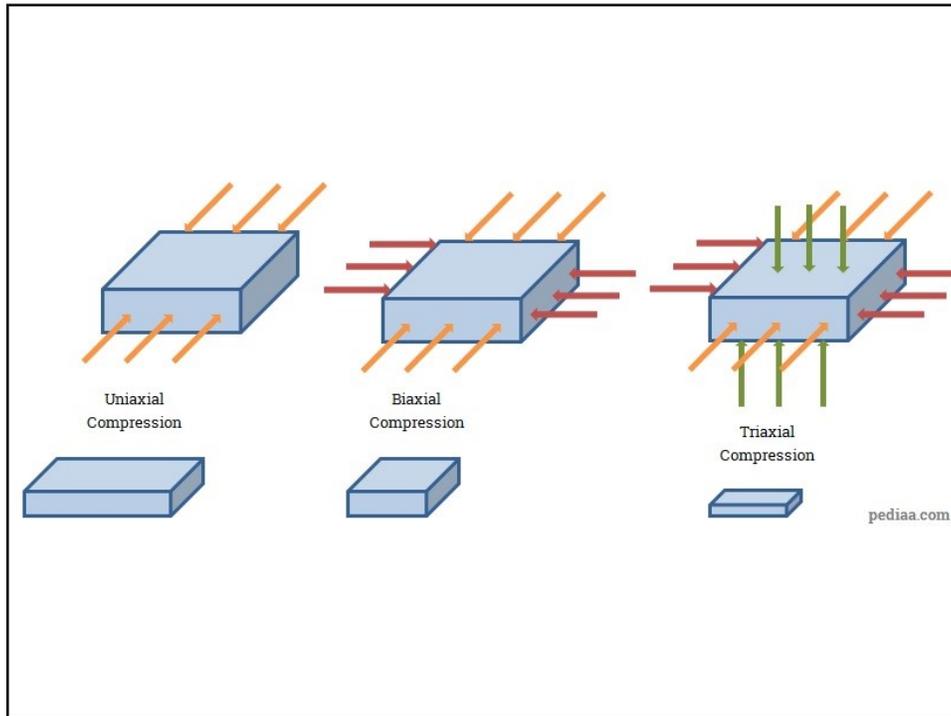
## **Conclusion**

**Strength  $\geq$  Stress/ deformation/ Failure criterion**

## Stress – strain relationship

- When a mechanical component is subjected to an external static force, a resisting force is setup within the component.
- Internal resisting force per unit area is called as stress.
- The stresses are tensile if fibers of component tend to elongate.
- The stresses are compressive if fibers of component tend to shorten.





## Stress – strain relationship

$$\sigma_t = \frac{P}{A}$$

Where  $\sigma_t$  = tensile stress

P = external force

A = cross-sectional area

$$\epsilon = \frac{\delta}{l}$$

$\epsilon$  = strain

$\delta$  = elongation of tension rod

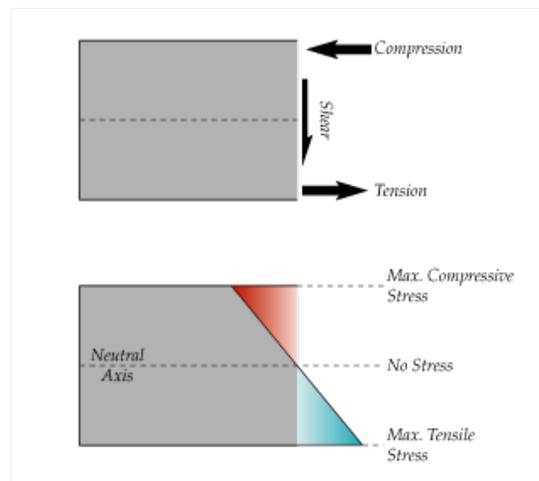
l = original length of rod

$$\delta = \frac{Pl}{AE}$$

The following assumptions should be made

1. The material is homogeneous.
2. The load is gradually applied.
3. The line of action of force P passes through the geometric axis of the cross – section.
4. The cross – section is uniform and free from the effects of stress concentration.

## Stresses due to bending moment



## Stresses due to bending moment

The bending stress in any fiber is given by

$$\sigma_b = \frac{M_b y_{\max}}{I} \quad \sigma \propto y$$

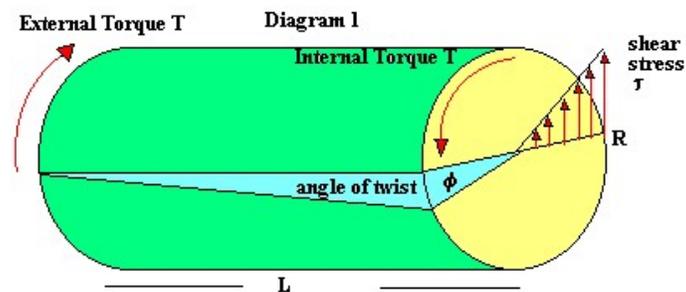
where

$\sigma_b$  = bending stress at a distance of  $y$  from neutral axis ( $\text{N/mm}^2$ )

$M_b$  = applied bending moment

$I$  = moment of inertia of cross-section about the neutral axis ( $\text{mm}^4$ )

## Stresses due to Torsional Moment (Torque)

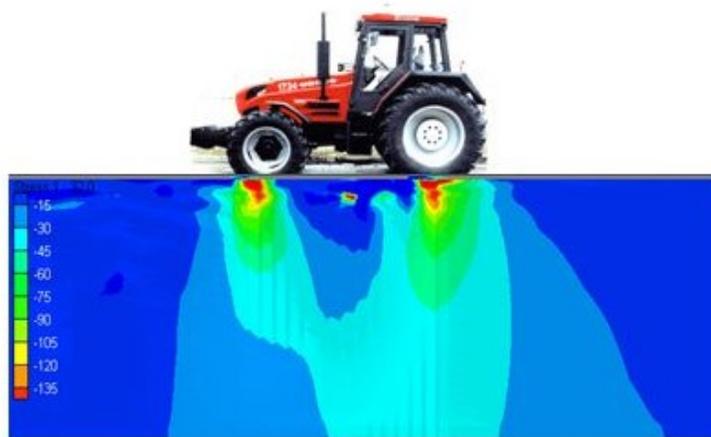


## Stresses due to torsional moment

The internal stresses, which are induced resist the action of twist, are called torsional shear stresses.

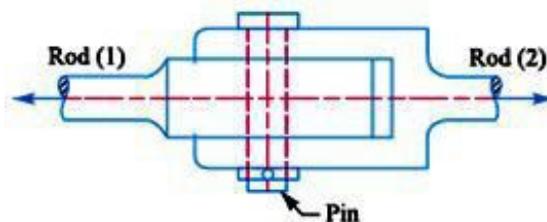
$$\tau = \frac{M_t r}{J}$$

## FEM Modelling of stress propagation in ANSYS



### Problem no.1

- Two circular rods of 50 mm diameter are connected by a knuckle joint, as shown in Figure, by a pin of 40 mm in diameter. If a pull of 120 kN acts at each end, find the stress in the rod and pin.



### Factor of safety (Safe-Fail Design)

Number of factors which are difficult to evaluate accurately in design analysis.

- Uncertainty in magnitude of external force acting on component
- Variations in property of material like yield strength or ultimate strength
- Variations in dimension of component due to imperfect workmanship.

- While designing a component, it is necessary to ensure sufficient reserve strength.
- It is ensured by factor of safety (FS).

$$FS = \frac{\text{failure stress}}{\text{allowable stress}}$$

*or*

$$FS = \frac{\text{failure load}}{\text{working load}}$$

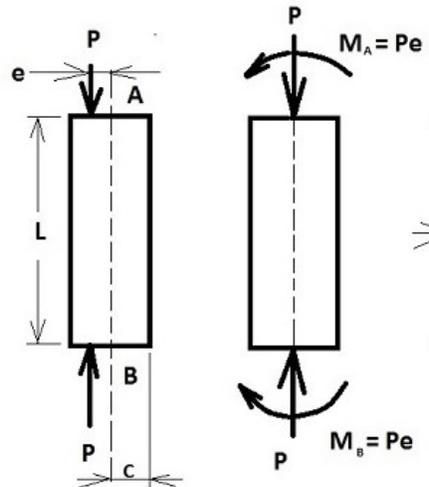
- For ductile materials  $\sigma = \frac{\sigma_{yt}}{FS}$
- For brittle materials  $\sigma = \frac{\sigma_{ut}}{FS}$

## Selection of Factor of safety

Depends upon two factors

- Material of component
- Strength – criterion used

## Eccentric Axial Loading



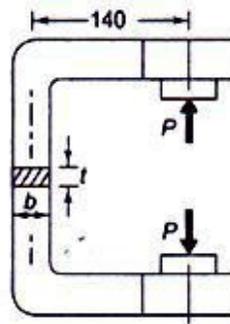
### Eccentric axial loading (cont...)

- If the line of action of force does not pass through the centroid of cross – section. The loading is said to be an eccentric loading.
- The resultant stress at the cross – section

$$\sigma = \frac{P}{A} \pm \frac{Pey}{I}$$

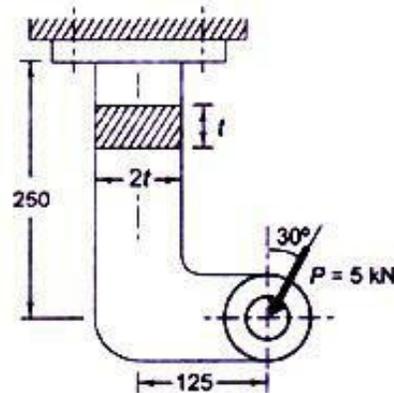
## Problem no.2

- Figure shows a C-clamp, which carries a load of 25 kN. The cross-section of the clamp is rectangular and the ratio of the width to thickness ( $b/t$ ) is 2:1. The clamp is made of cast steel of grade 20-40 ( $S_{ut}=400 \text{ N/mm}^2$ ) and the factor of safety is 4. Determine the dimensions of the cross-section of the clamp.



## Problem no.3

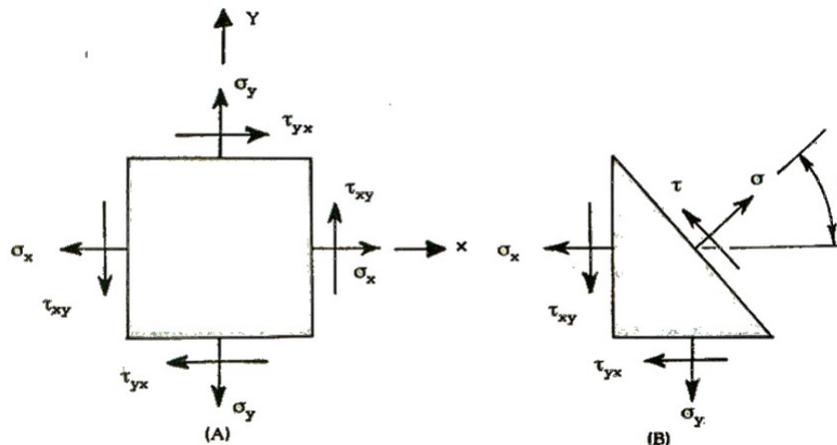
- A bracket, made of steel FeE ( $S_{yt}=200 \text{ N/mm}^2$ ) and subjected to a force of 5 kN acting at an angle of  $30^\circ$  to the vertical, is shown in Figure. The factor of safety is 4. Determine the dimensions of the cross-section of the bracket.



## Principal stresses

- There are two types of stresses – Normal stresses ( $\sigma_x, \sigma_y, \sigma_z$ ) and shear stresses ( $\tau_{xy}, \tau_{yx}$ ).
- Predicting failure in members subjected to uniaxial stress is simple and straight-forward.
- But the problem of predicting the failure stresses for members subjected to **bi-axial, tri-axial stresses or combination of normal and shear stresses** (e.g. a transmission shaft) is much more complicated. For design, it is necessary to determine the state of stresses (principal

## Two dimensional state of stress



$$\sigma = \left( \frac{\sigma_x + \sigma_y}{2} \right) + \left( \frac{\sigma_x - \sigma_y}{2} \right) \cos 2\theta + \tau_{xy} \sin 2\theta$$

and

$$\tau = - \left( \frac{\sigma_x - \sigma_y}{2} \right) \sin 2\theta + \tau_{xy} \cos 2\theta$$

$$\tan 2\theta = \frac{2\tau_{xy}}{\sigma_x - \sigma_y}$$

Principal stresses

$$\sigma_1 = \left( \frac{\sigma_x + \sigma_y}{2} \right) + \sqrt{\left( \frac{\sigma_x - \sigma_y}{2} \right)^2 + (\tau_{xy})^2}$$

$$\sigma_2 = \left( \frac{\sigma_x + \sigma_y}{2} \right) - \sqrt{\left( \frac{\sigma_x - \sigma_y}{2} \right)^2 + (\tau_{xy})^2}$$

Principal shear stress

$$\tau_{\max} = \pm \sqrt{\left( \frac{\sigma_x - \sigma_y}{2} \right)^2 + (\tau_{xy})^2}$$

$$\tan \theta_s = - \left( \frac{\sigma_x - \sigma_y}{2\tau_{xy}} \right)$$

## **Theories of failure (Application of principal stresses)**

The principal theories of failure for a member subjected to bi-axial stress are as follows:

- 1. Maximum principal (or normal) stress theory (Rankine's theory).**
- 2. Maximum shear stress theory (Guest's or Tresca's theory).**
3. Maximum principal (or normal) strain theory (Saint Venant theory).
4. Maximum strain energy theory (Haigh's theory).
- 5. Maximum distortion energy theory (Hencky and Von Mises theory)**

## Maximum principal or normal stress theory (Rankine's theory)

- The failure or yielding occurs at a point in a member when the maximum principal or normal stress in a bi-axial stress system reaches the limiting strength of the material in a simple tension test.
- The limiting strength for ductile materials is yield point stress and for brittle materials the limiting strength is ultimate stress.

## Maximum Principal or Normal Stress Theory (Rankine's Theory)

$$\sigma_{t1} = \frac{\sigma_{yt}}{FS}, \text{ for ductile materials}$$

$$\sigma_{t1} = \frac{\sigma_u}{FS}, \text{ for brittle materials}$$

$\sigma_{yt}$  = Yield point stress in tension as determined from simple tension test.

$\sigma_u$  = Ultimate stress.

- It ignores the possibility of failure due to shearing stress, therefore it is not used for ductile materials.
- However, for brittle materials which are relatively strong in shear but weak in tension or compression, this theory is generally used.

### Maximum Shear Stress Theory (Guest's or Tresca's Theory)

$$\tau_{\max} = \frac{\tau_{yt}}{FS}$$

where  $\tau_{\max}$  = maximum shear stress in a bi - axial stress system

$\tau_{yt}$  = Shear stress at yield point as determined from simple tension test

Since the shear stress at yield point in a simple tension test is equal to one-half the yield stress in tension

$$\tau_{\max} = \frac{\sigma_{yt}}{2 \times FS}$$

This theory is mostly used for designing members of ductile materials.

### Maximum Distortion Energy Theory (Hencky and Von Mises Theory)

- The failure or yielding occurs at a point in a member when the distortion strain energy (also called shear strain energy) per unit volume in a bi-axial stress system reaches the limiting distortion energy (i.e. distortion energy at yield point) per unit volume as determined from a simple tension test.

- The maximum distortion energy theory for yielding is

$$(\sigma_{t1})^2 + (\sigma_{t2})^2 - \sigma_{t1} \times \sigma_{t2} = \left( \frac{\sigma_{yt}}{FS} \right)^2$$

- This theory is mostly used for ductile materials.

In case of combined bending and torsional moments, there is a normal stress  $\sigma_x$  accompanied by the torsional shear stress  $\tau_{xy}$ .

Substituting  $\sigma_y = \sigma_z = \tau_{yz} = \tau_{zx} = 0$  in Eq.

$$\sigma = \sqrt{\sigma_x^2 + 3\tau_{xy}^2}$$

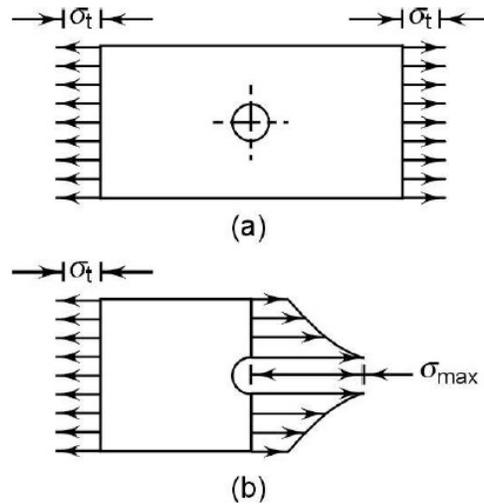
### Problem no.4

The load on a bolt consists of an axial pull of 10 kN together with a transverse shear force of 5 kN. Find the diameter of bolt required according to

1. Maximum principal stress theory;
2. Maximum shear stress theory;
3. Maximum distortion energy theory.

Take permissible tensile stress at elastic limit = 100 MPa and poisson's ratio = 0.3.

## Stress Concentration in static loading



## Stress Concentration Factor ( $K_t$ )

Elementary equations:

$$\sigma_t = \frac{P}{A} \quad \sigma_b = \frac{M_b y}{I} \quad \tau = \frac{M_t r}{J}$$

**Stress concentration** is defined as the localization of high stresses due to the **irregularities** presents in the component and **abrupt changes** of the cross section.

**Stress concentration factor** ( $K_t$ ) is defined as

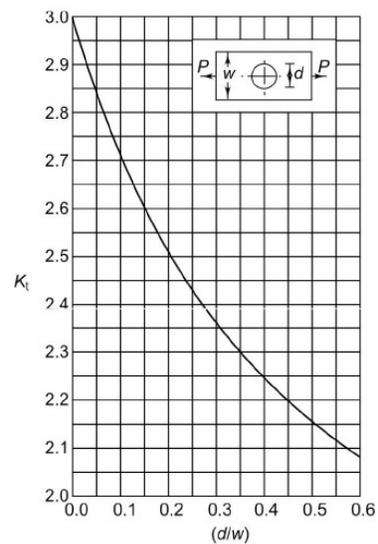
$$K_t = \frac{\text{highest value of actual stress near discontinuity}}{\text{nominal stresses obtained by elementary equations for minimal cross - section}}$$

Stress concentration factor for  
**Different Irregularities** (Follow any  
 design **data book**)

The nominal stress is given by

$$\sigma_0 = \frac{P}{(w-d)t}$$

where  $t$  is the plate thickness.

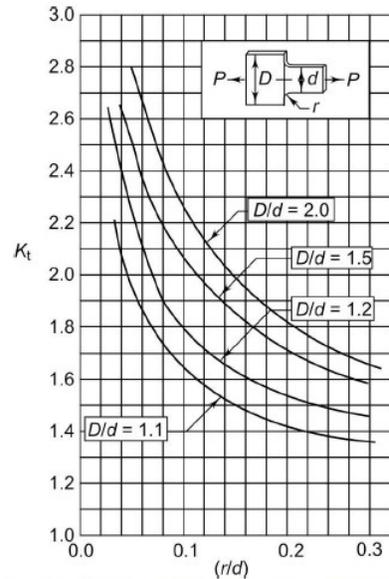


*Stress Concentration Factor (Rectangular Plate with  
 Transverse Hole in Tension or Compression)*

The nominal stress is given by

$$\sigma_0 = \frac{P}{dt}$$

where  $t$  is the plate thickness.

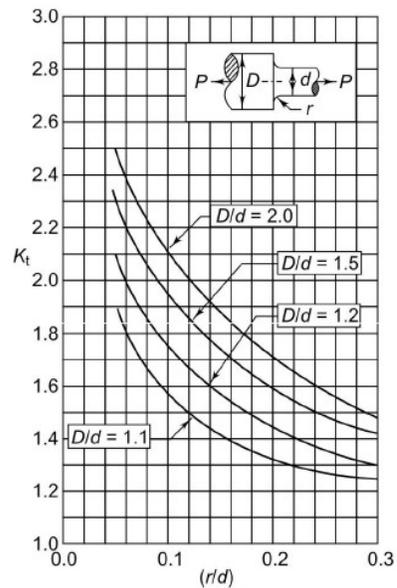


*Stress Concentration Factor (Flat Plate with Shoulder Fillet in Tension or Compression)*

The nominal stress is given by

$$\sigma_0 = \frac{P}{\frac{\pi}{4}d^2}$$

where  $d$  is the diameter on the small end.



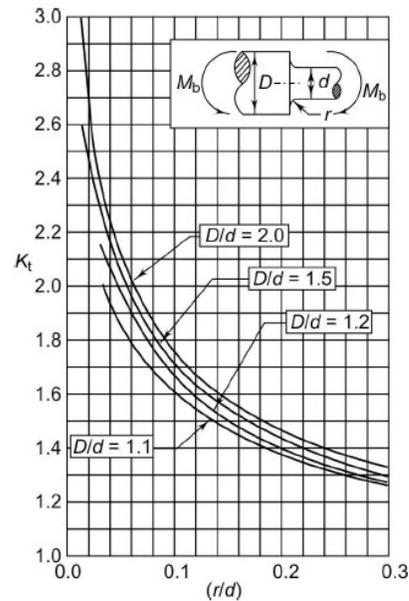
*Stress Concentration Factor (Round shaft with Shoulder Fillet in Tension)*

The nominal stress is given by

$$\sigma_0 = \frac{M_b y}{I}$$

where  $d$  is the diameter on the smaller end.

$$I = \frac{\pi d^4}{64} \quad \text{and} \quad y = \frac{d}{2}$$



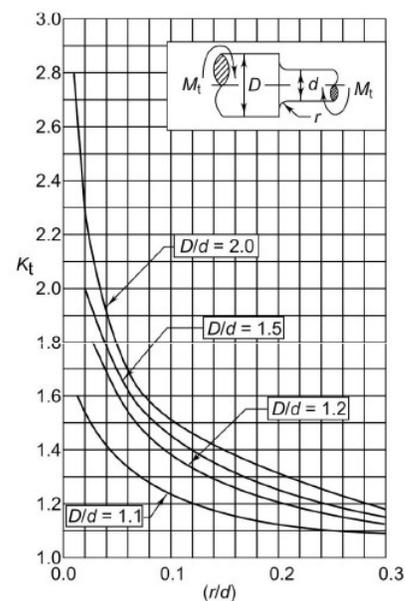
*Stress Concentration Factor (Round Shaft with Shoulder Fillet in Bending)*

The nominal stress is given by

$$\tau_0 = \frac{M_t r}{J}$$

where  $d$  is the diameter on the smaller end.

$$J = \frac{\pi d^4}{32} \quad \text{and} \quad r = \frac{d}{2}$$



*Stress Concentration Factor (Round Shaft with Fillet in Torsion)*

